Blocks and Contexts: Exploring Scientific Algorithms

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SciPy 07

August 17, 2007

Scientists often know how to model their problems in software.

Its exploring them that is hard.

How do we make it easier?

Fortran Example

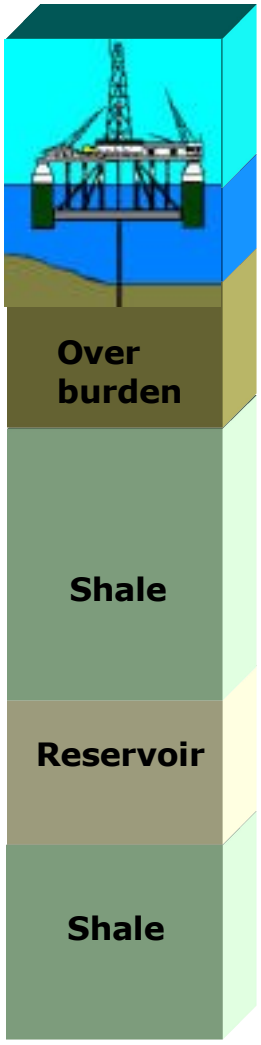
```
      PROGRAM ONE_D_MOTION
C Program for the motion of a particle subject to an external
C force f(x) = -x. The position and velocity of the particle
C are written out at every 500 steps.
      PARAMETER (N=10001,IN=500)
      REAL T(N),V(N),X(N)
C Assign constants, initial position, and initial velocity
      PI   = 4.0*ATAN(1.0)
      DT   = 2.0*PI/FLOAT(N-1)
      X(1) = 0.0
      T(1) = 0.0
      V(1) = 1.0
C Recursion for position and velocity at later time
      DO      100  I = 1, N-1
        T(I+1) = DT*I
        X(I+1) = X(I)+V(I)*DT
        V(I+1) = V(I)-X(I)*DT
  100 CONTINUE
C Write the position and velocity every 500 steps
      WRITE (6,999) (T(I),X(I),V(I),I=1,N,IN)
      STOP
```

From: "An Introduction to Computational Physics," by Tao Pang

Typical Scientific Code

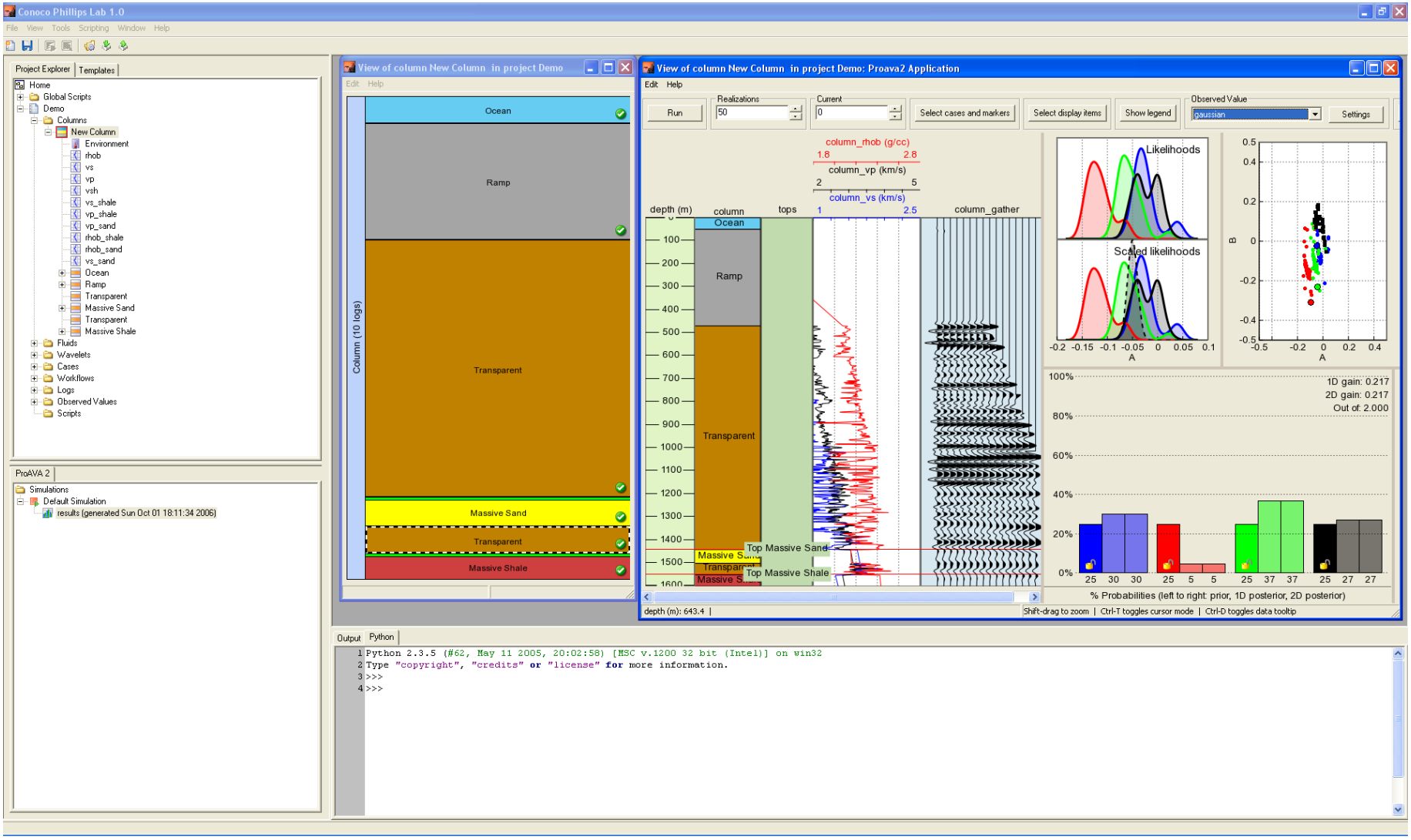
```
from numpy import arange, ravel, minimum
from scipy.integrate import odeint

# Define functions.
def growth_structure(y,t, k1, k2, gammadot):
    res = -k1*gammadot*y+k2*(1.0-y)
    return res

def growth(t, y, k1, k2, gammadot, gammaC0, G, k, m, n,):
    visc=(1.0-y) * k * gammadot**n
    gammaE = gammadot*t
    gammaC = gammaC0 * y**m
    elastic = y * G * minimum(gammaE, gammaC)
    total = visc + elastic
    return visc, elastic, total

# Set up algorithm parameters and intial guesses...
k=400.0; n=0.7; gammadotgrowth=20.0; gammadotrelax=0.0
gammaC0 =0.5; m=-0.33; G=25000.0; k1=2.0; k2=1.0
y0 = 1.0
x1 = arange(0.0, .5, 0.005)

# The actual calculation.
y1 = odeint(growth_structure, y0, x1, args=(k1,k2,gammadotgrowth))
y1 = ravel(y1)
viscous, elastic, total = growth(x1, y1, k1, k2, gammadotgrowth,
                                 gammaC0, G, k, m, n)
```

Complex Problems, Simple Algorithms




```
# ocean
vp = 1.5
vs = 1e-5
rhob = 1.05

# interpolation region


# bulk shale
xsh = xsh_shale1
vp, vs, rhob = backus_avg(xsh, vp_sh, vs_sh, rhob_sh,
                          vp_s, vs_s, rhob_s)

# fining upward
xsh = linear([top, base], [max_xsh, min_xsh], len(vp_sh))
vp, vs, rhob = backus_avg(xsh, vp_sh, vs_sh, rhob_sh,
                          vp_s, vs_s, rhob_s)

# bulk shale
xsh = xsh_shale2
vp, vs, rhob = backus_avg(xsh, vp_sh, vs_sh, rhob_sh,
                          vp_s, vs_s, rhob_s)
```

Stochastic Modeling Tool

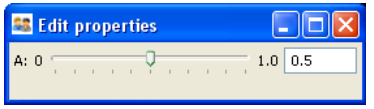


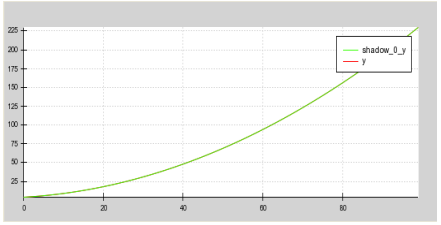
Analysis of Models

Scientific Model

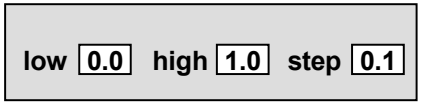
```
a=1
b=2
c=3
y = a*x**2+b*x+c
```

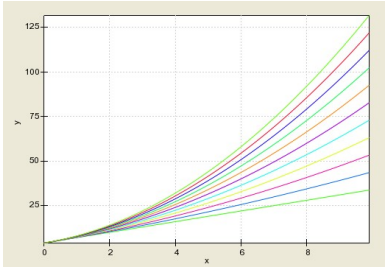
"What-if" analysis:



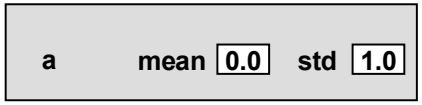


Parametric Studies:





Monte Carlo:



Inversion: Given y, invert for a, b, and c.

Blocks and Contexts

Code Block

```
a=1
b=2
c=3
y = a*x**2+b*x+c
```

Code blocks are a set of executable instructions.

Context

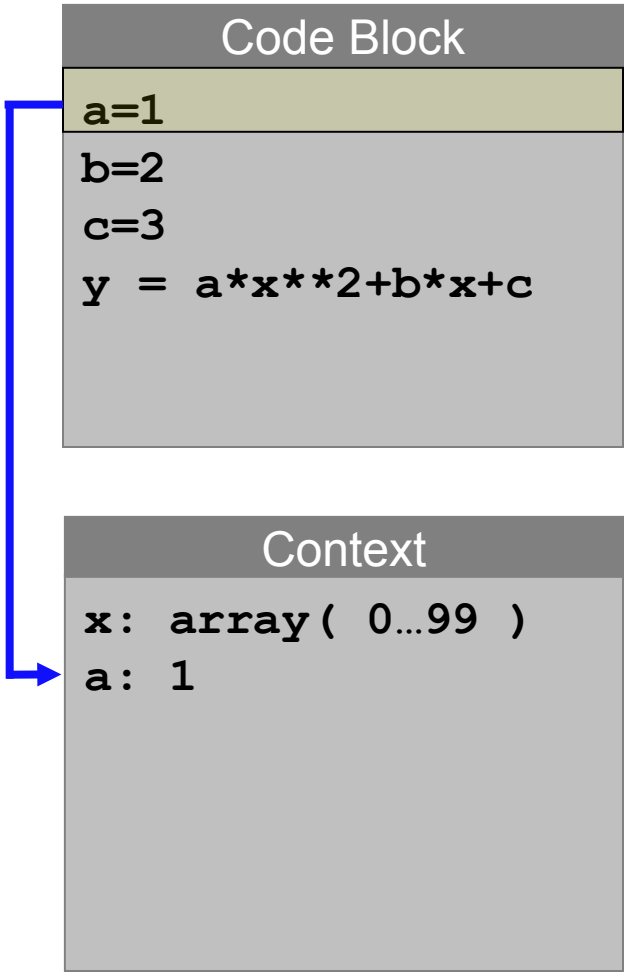
```
x: array( 0…99 )
```

Contexts or “namespaces” is a mapping of names to values.

Python Code Execution

```
# What really happens when you execute the following code?
a = 1
b = 2
c = 3
y = a*x**2+b*x+c
```

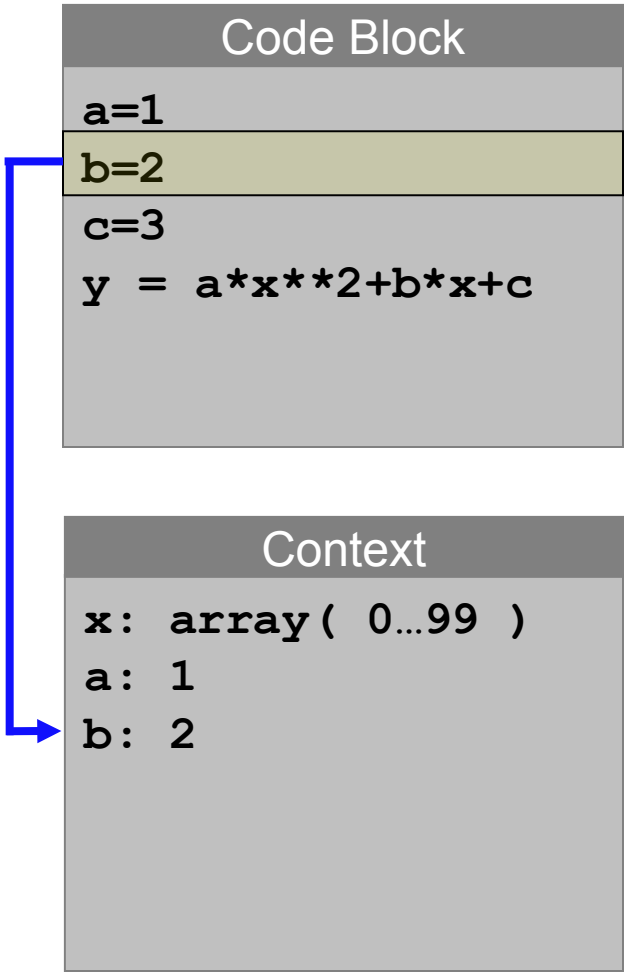
Blocks and Contexts



Code blocks are a set of executable instructions.

Contexts or “namespaces” is a mapping of names to values. Here, we’ll assume we started with ‘x’ already in the namespace.

Blocks and Contexts



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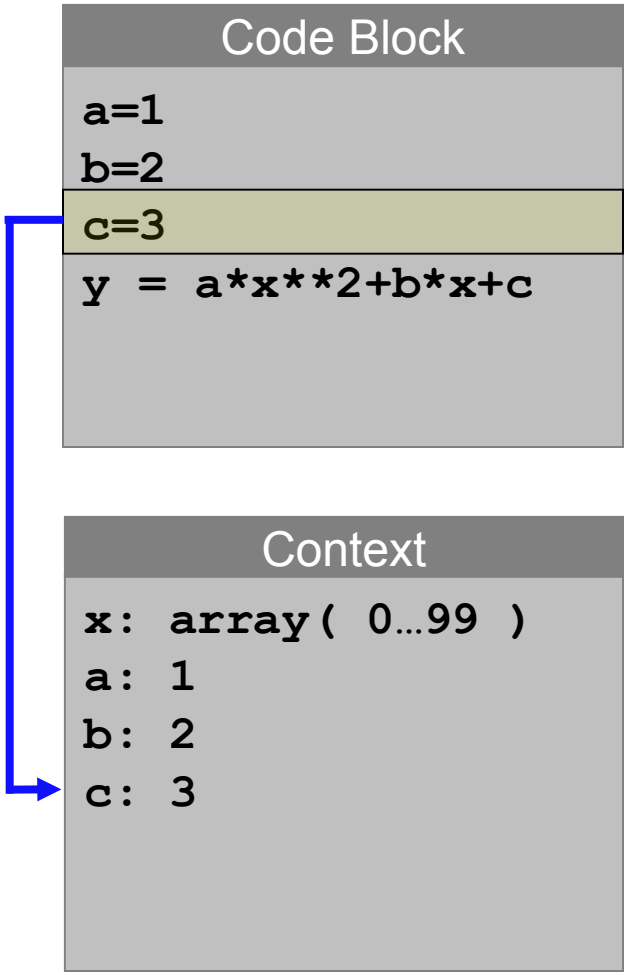
Blocks and Contexts



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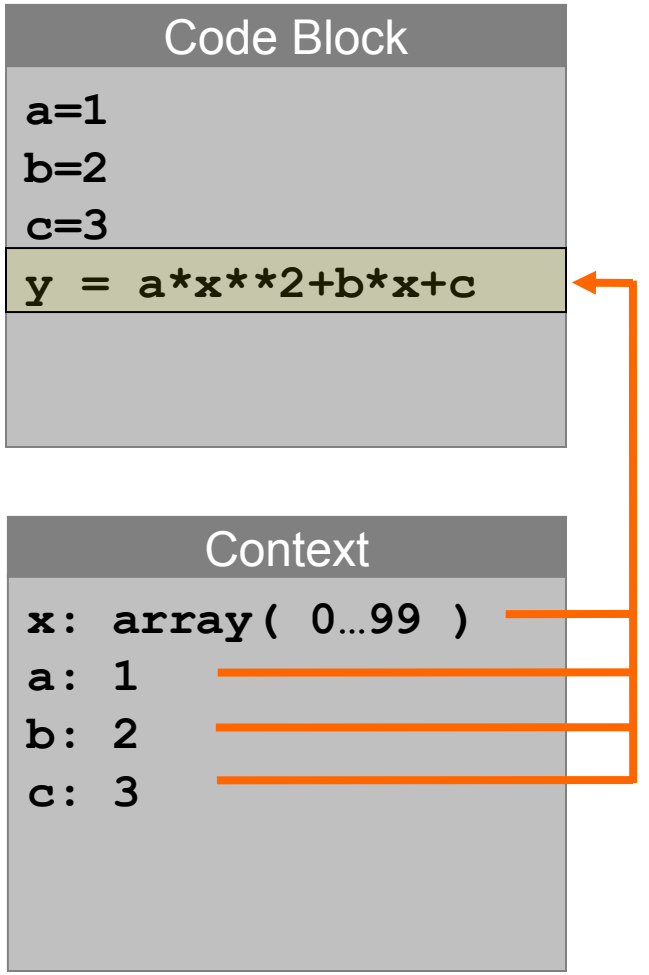
Blocks and Contexts



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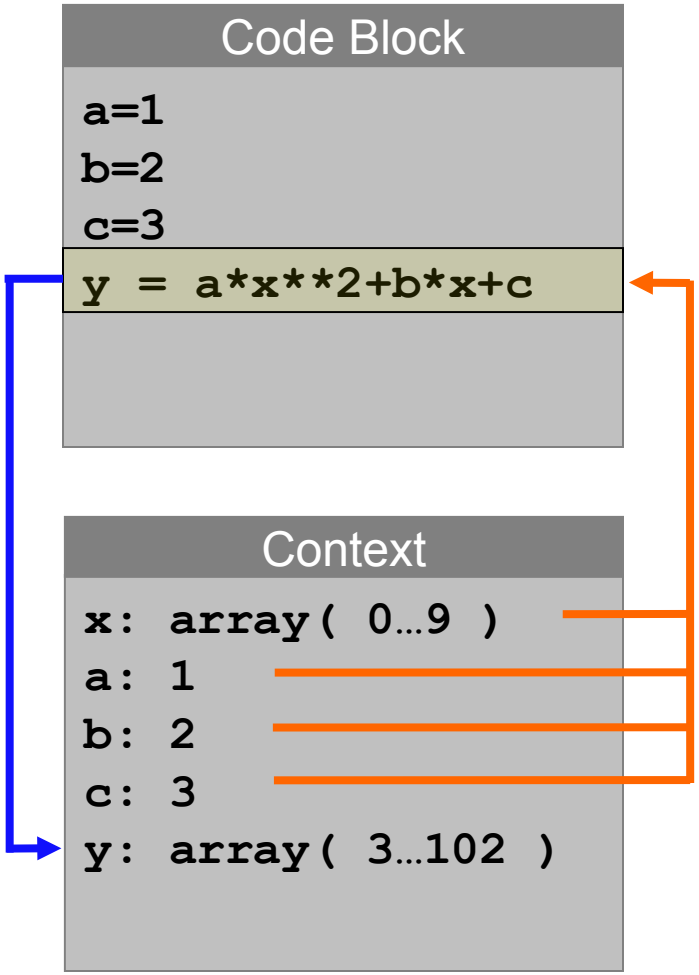
Blocks and Contexts



Code blocks are a set of executable instructions.

Contexts or “namespaces” is a mapping of names to values.

exec in a dictionary

Code Block

```
a=1
b=2
c=3
y = a*x**2+b*x+c
```

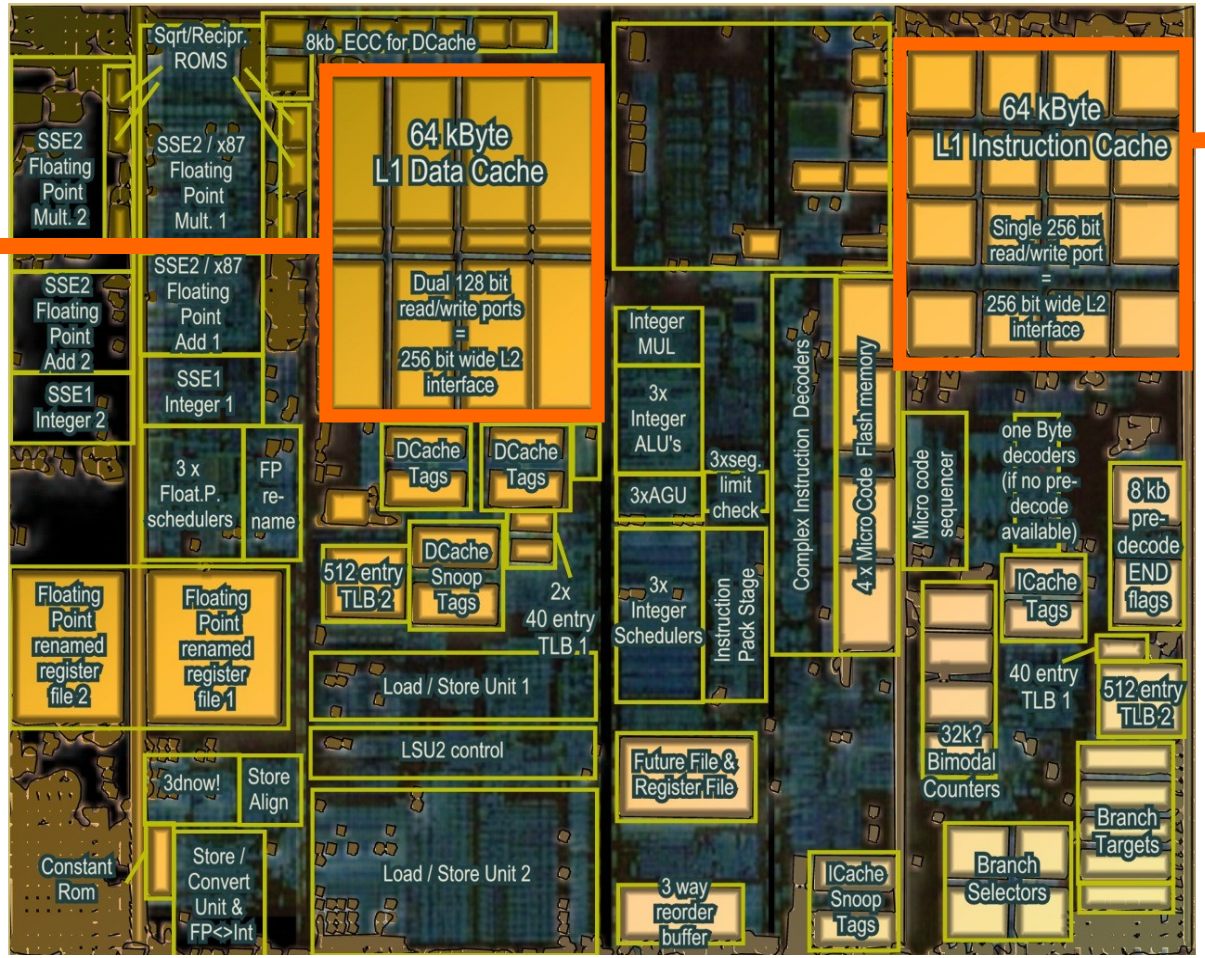
Context

```
x: array( 0…9 )
a: 1
b: 2
c: 3
y: array( 3…102 )
```

```
# set up context and load with 'x'
>>> context = {}
>>> context['x'] = arange(10.)

# execute code block in context
>>> code = '''
a = 1
b = 2
c = 3
y = a*x**2+b*x+c
'''
>>> exec code in {}, context

# y was computed and put in context.
>>> context['y']
array(3...102)
```

Single Core for AMD's upcoming Quad-core processor

Data Cache



Instruction Cache

Contexts with Events

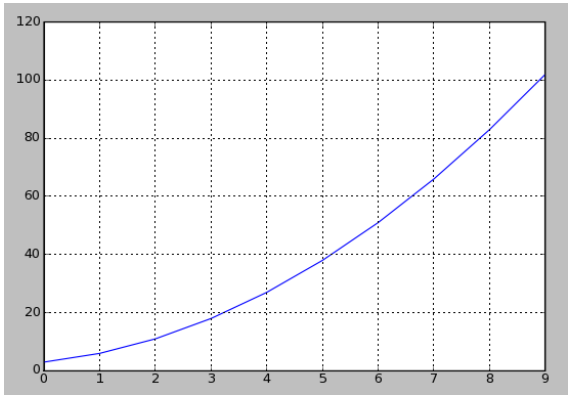
Code Block

```
a=1
b=2
c=3
y = a*x**2+b*x+c
```

Context

```
x: array( 0…9 )
a: 1
b: 2
c: 3
y: array( 3…102 )
```

Events Fire when data changes



Updating Data View

Contexts with Events

```
# set up context and load with 'x'
>>> context = DataContext()
>>> context['x'] = arange(10.)

# hook up listener for changes to context.
>>> def printer(event):
...     print 'added:', event.added
>>> context.on_trait_change(printer, 'items_modified')

# execute code block in context
>>> code = '''
a = 1
b = 2
c = 3
y = a*x**2+b*x+c
'''
>>> exec code in {}, context
added: ['a']
added: ['b']
added: ['c']
added: ['y']
```

Text printed by the listener defined above.

Interacting with a Variable

Suppose we want to do “what-if” analysis to see how changes to ‘a’ affect our model.

Original Block

```
a=1
b=2
c=3
y = a*x**2+b*x+c
```

Dependency Analysis:
Extract sub-block
that is affected by **a**

What-if Block

```
y = a*x**2+b*x+c
```

Context

```
x: array( 0…9 )
a: 1
b: 2
c: 3
y: array( 3…102 )
```

Dependency Analysis

```
# Create a "Block" that represents/analyzes code
>>> code = '''
a = 1
b = 2
c = 3
y = a*x**2+b*x+c
'''
>>> block = Block(code)

# Calculate the sub-block affected by updates to x
>>> sub_block = block.restrict(inputs=['a'])
>>> print compiler_unparse.unparse(sub_block.ast)
y = a*x**2+b*x+c

>>> sub_block.inputs
set(['a', 'x', 'c', 'b'])

>>> sub_block.outputs
set(['y'])
```

Interacting with a Variable

What-if Block

```
y = a*x**2+b*x+c
```

Context

```
x: array( 0…9 )
a: 1
b: 2
c: 3
y: array( 3…102 )
```

A “Shadow” context refers back to original context for all static values

What-if Context

```
x: array( 0…9 )
a: 1
b: 2
c: 3
y: array( 3…102 )
```

Interacting with a Variable

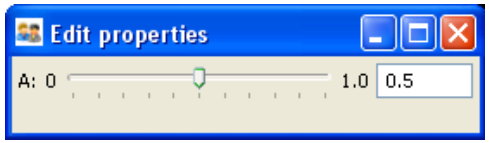
What-if Block

```
y = a*x**2+b*x+c
```

Changes to Block inputs re-computes outputs.

Context

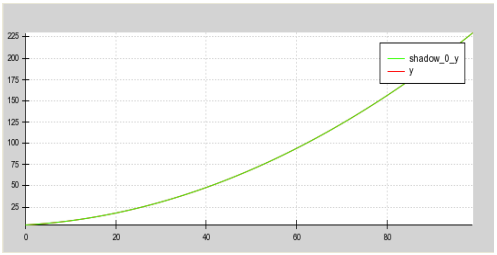
```
x: array( 0…9 )
a: 1
b: 2
c: 3
y: array( 3…102 )
```



"What-if" analysis on variable `'a'`

What-if Context

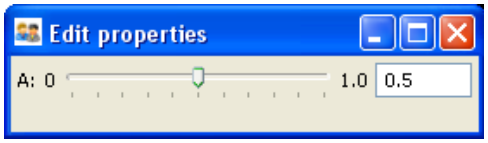
```
x: array( 0…9 )
a: 0.5
b: 2
c: 3
y: array(3…61.5)
```



Plots update to show new values over old

Implementing Shadow Contexts

- Writes always happen to the Primary Context.
- Reads first try in Primary Context. If that fails, they try the Secondary Context.



What-if Block

```
y = a*x**2+b*x+c
```

What-if Context

"Primary" Context

```
a: 0.5
y: array( 3…61.5 )
```

"Secondary" Context

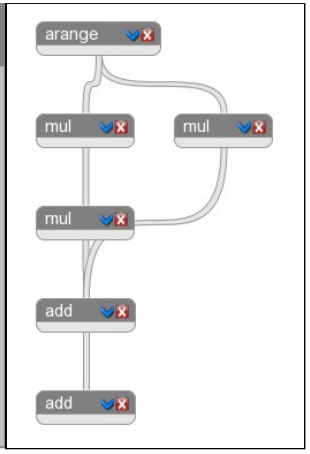
```
x: array( 0…9 )
a: 1
b: 2
c: 3
y: array( 3…102 )
```

Functions vs. Data

- Function Context accepts only Functions.
- Data Context holds everything else.
- This prevents the data context from getting cluttered.

Block

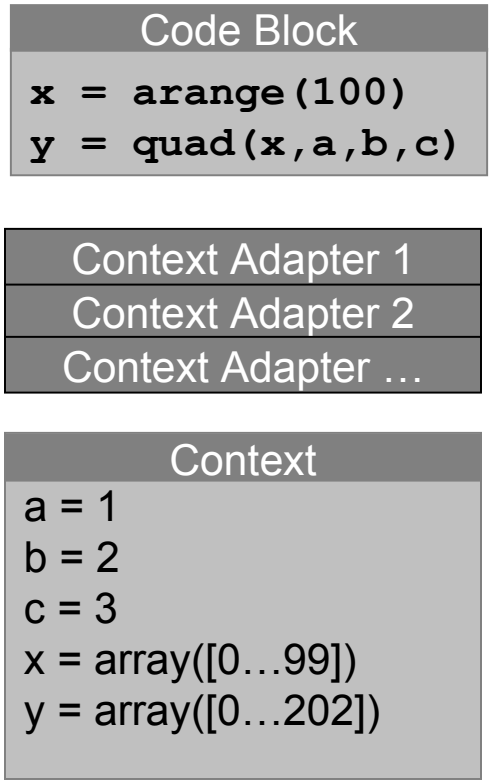
```
from my_operator import add, mul
from numpy import arange
x = arange(0,10,.1)
x1 = mul(x,x)
t1 = mul(a,x1)
t2 = mul(b, x)
t3 = add(t1,t2)
y = add(t3,c)
```



Canvas Context

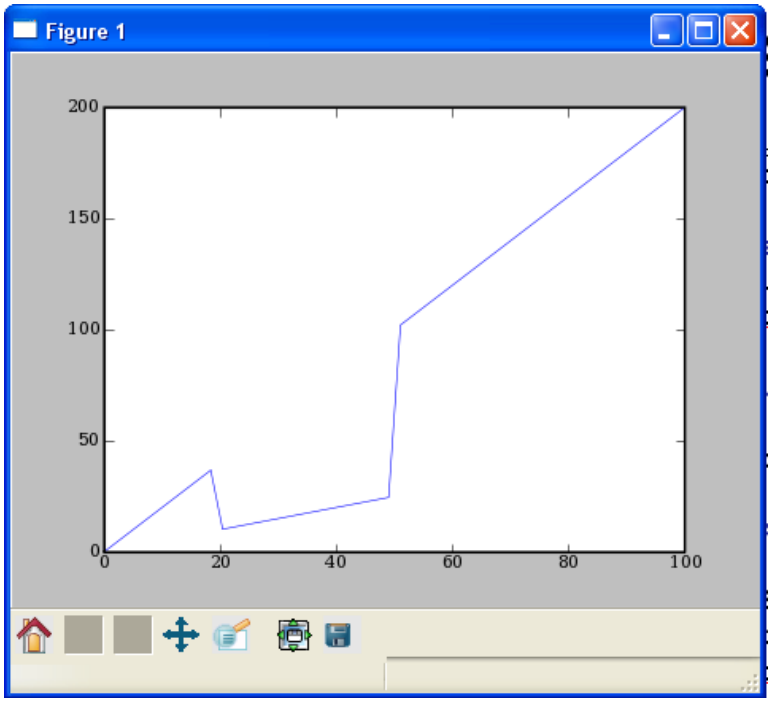
Function Context	Data Context
arange add mul	a: 0.5 b: 3.0 c: 4.0 x: array(0…9) ...

Context Adapters



A Masking Adapter

```
context = AdaptedDataContext(context=DataContext())

# Add some depth values as data in the context.
depth=linspace(0,100)
context.update(depth=depth)

# Calculate a pressure based on depth.
code = "pressure = depth*2.0"
exec code in globals(), context

# "Mask" context so that it only a
ffects certain ranges of data.
mask=(20.0<=depth) & (depth<=50.0)
adapter = MaskingAdapter(mask=mask)
context.push_adapter(adapter)

# Calculate new pressures for masked values.
code = "pressure = depth/2.0"
exec code in globals(), context

# Unmask the context
context.pop_adapter()
```



Using with inside a context.

```
# Calculate pressure at depth using
# a simple formula.
depth=linspace(0,100)
pressure = depth*2.0

# "Mask" context so that code only
# affects certain ranges of data.
with Mask((20.0<=depth) & (depth<=50.0)):
    # In this region, use a different
    # formula for pressure.
    pressure = depth/2.0
```